

WebControl™ PLC

User Guide

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Firmware Version:	3.0.6
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1 Introduction

This document provides an overview of the technical aspects of using WebControl™ PLC. It describes the inputs and outputs offered by the PLC version of the WebControl™ hardware and firmware. WebControl PLC Programming Guide is in chapter 6 of this document. WebControl™ PLC is different from WebControl™ BRE. PLC version firmware provides greater flexibility in I/O control but also expects user having the knowledge to write assembly like PLC program. It can compare the input and output value, between analog inputs, digital inputs, or timers. WebControl can operate without network connection on its own. To assist writing PLC code is not included in the regular support for WebControl™ PLC configuration.

1.1 Scope

The scope of this document is to be a guide for configuring and using the features provided by WebControl™. The reader is expected to be technically competent in all the technical areas within this document, and is strongly advised to use this document along side the other reference material listed in the reference section.

1.2 References

The following references are referred to through out this document. It is expected that the reader will use these along with this document in order to understand and use WebControl™ PLC.

Reference	Description
Ref1	WebControl™ PLC Programming Guide (chapter 6)
Ref2	This guide for how to configure WebControl™ through web GUI
Ref3	Wiring diagram of the WebControl™

1.3 Table of Definitions

The following table is a list of definitions used though out the document.

Definition	Description
HTTP	Hypertext transfer protocol
DNS	Domain name server
SMTP	Simple mail transport protocol
SNTP	Simple network time protocol
1-wire	Special bidirectional serial data bus from Maxim
RH	Relative humidity
NetBios	Human readable name used as an alternative to an IP address for accessing the server on a network. E.g. http://WebControl™
IP	Internet protocol
DHCP	Dynamic host configuration protocol

ROM	Read only memory
PLC	Programmable Logic Controller

2 WebControl™ I/O

The current hardware version of WebControl™ is equipped with a number of inputs and outputs; these are shown in below in figure 1.0.

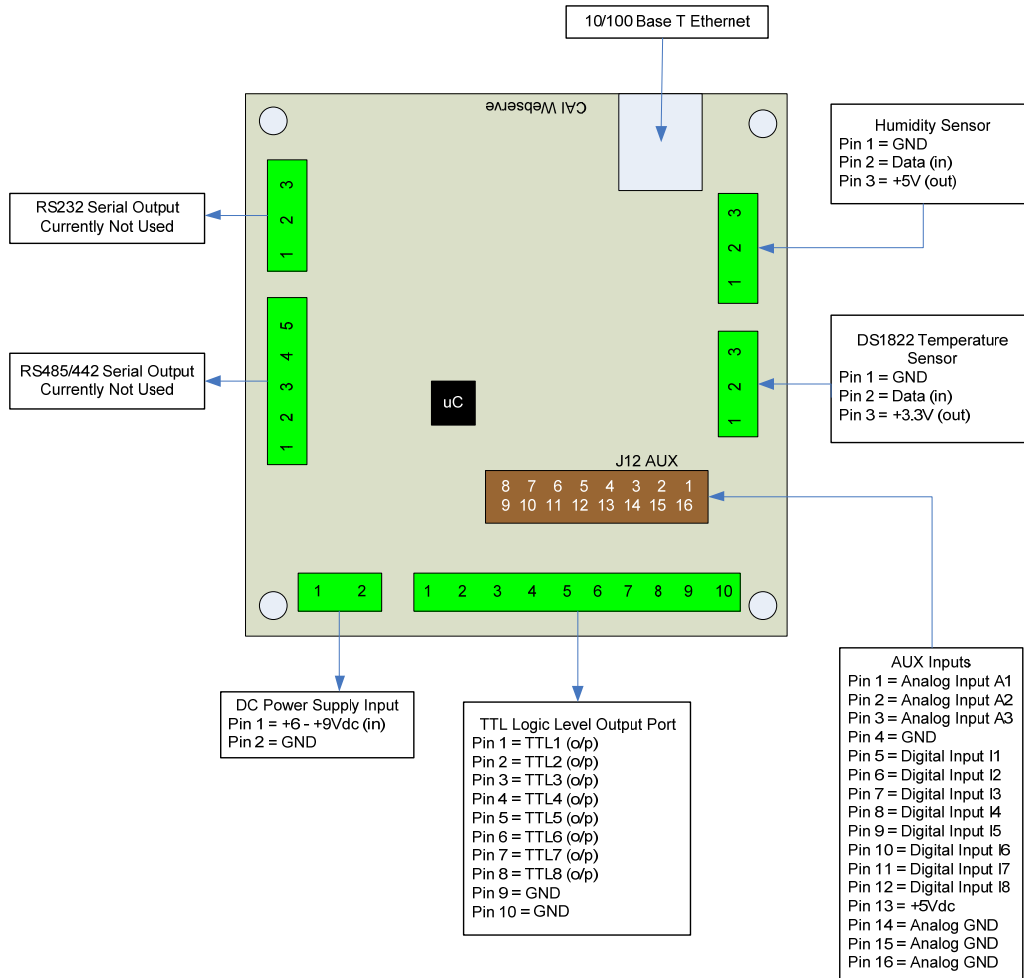


Figure 1.0 WebControl™ PCB inputs and outputs diagram

2.1 Serial Data Ports

Currently the RS232 and RS485/442 serial data ports provided by the hardware are not used by the firmware. The chip for those two protocols is not on the board.

2.2 Power Supply Inputs

The DC power supply input is the main DC supply to the board. The input voltage range is 7.5 – 9V DC. Any voltage greater than 12V applied to this input may overheat the board.

2.3 TTL Output Port

The TTL logic level output port has 8 TTL outputs that can each be set or cleared using web GUI command codes, or by setting up a PLC using the available inputs so that the particular output is set when a particular input condition is met. The maximum current that can be sourced or sunk by one of these outputs at a time is 20mA or 100mA for the whole board. TTL 0 level defined as 0-2V, and TTL 1 level is defined 3-5V with TTL 0 almost 0V and TTL 1 almost 5V depending on the load. TTL output current is capable to drive standard solid state relay, but not be able to drive those coil based relays.

2.4 AUX Input Port

The AUX input connector offers digital and analog inputs that can be configured to set a TTL output upon a single input or a combination of inputs. 3 analog inputs are offered that have an input range of 0 – 10Vdc. 8 digital inputs are offered that use TTL input levels (0 and 5Vdc). The AUX input pin out diagram [ref3] shows the pin out of this port in more detail. Connector is TYCO ELECTRONICS - 1658622-3 .

2.5 DS1822 Temperature Sensor Input

The temperature sensor input allows up to eight Maxim DS1822/DS18B20 1-wire temperature sensors to be connected. These sensors can then display the temperature via the HTTP server or be used as inputs to the Boolean engine controlling the TTL output port. When DC supply voltage is too low, temp sensor may not have stable reading, due to the protection diode in the circuit. Please check your supply voltage when you noticed the temp sensor reading not correct.

2.6 Humidity Sensor Input

The current WebControl™ hardware has been designed to use the Honeywell 4000 series relative humidity sensor devices. Using any other humidity sensor without careful consideration may result in malfunction of this feature. The RH sensor can be used to display relative humidity via HTTP or be used to control the TTL outputs as an input into the PLC.

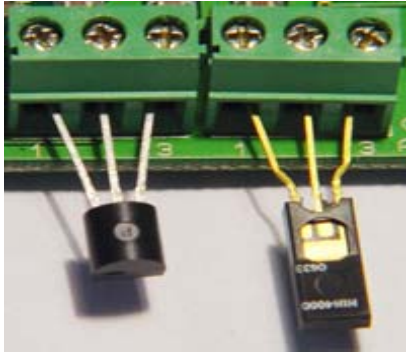


Figure 2.0 WebControl™ sensor connection

Please make sure the temp sensor and humidity sensor connected similar to this picture. Reverse the polarity may cause damage to the board.

3 WebControl™ PLC Web GUI Configuration

To access WebControl™ PLC, connect WebControl™ to the network and power supply. If you have DHCP server in your network, please check your DHCP server log for which IP address assigned to the board. Each WebControl™ PLC board has its unique MAC address. Look in the HDPC log for matching MAC address you can find its IP address. If you do not have DHCP server in your network, the default IP address will be 192.168.1.15. From any computer with browser points to that IP address: <http://ww.xx.yy.zz> You will be prompt for login. The default user ID and password is: “**admin/password**”, all in lower case. You will see this page once logged in:

CAI WebControl PLC

Version: v03.00.06 IpAddress: 192.168.12.15 Name: WEBCONTROL 06/29/2010 13:57:18

System Status

System Status

Output Control

I/O Setup

Email Setup

Temperature Sensor Setup

PLC Program

General Setup

Network Setup

Help

Outputs								
	1	2	3	4	5	6	7	8
TTL Output Bits	0	0	0	0	0	0	0	0
16 Bit Signed Vars	0	0	0	0	0	0	0	0

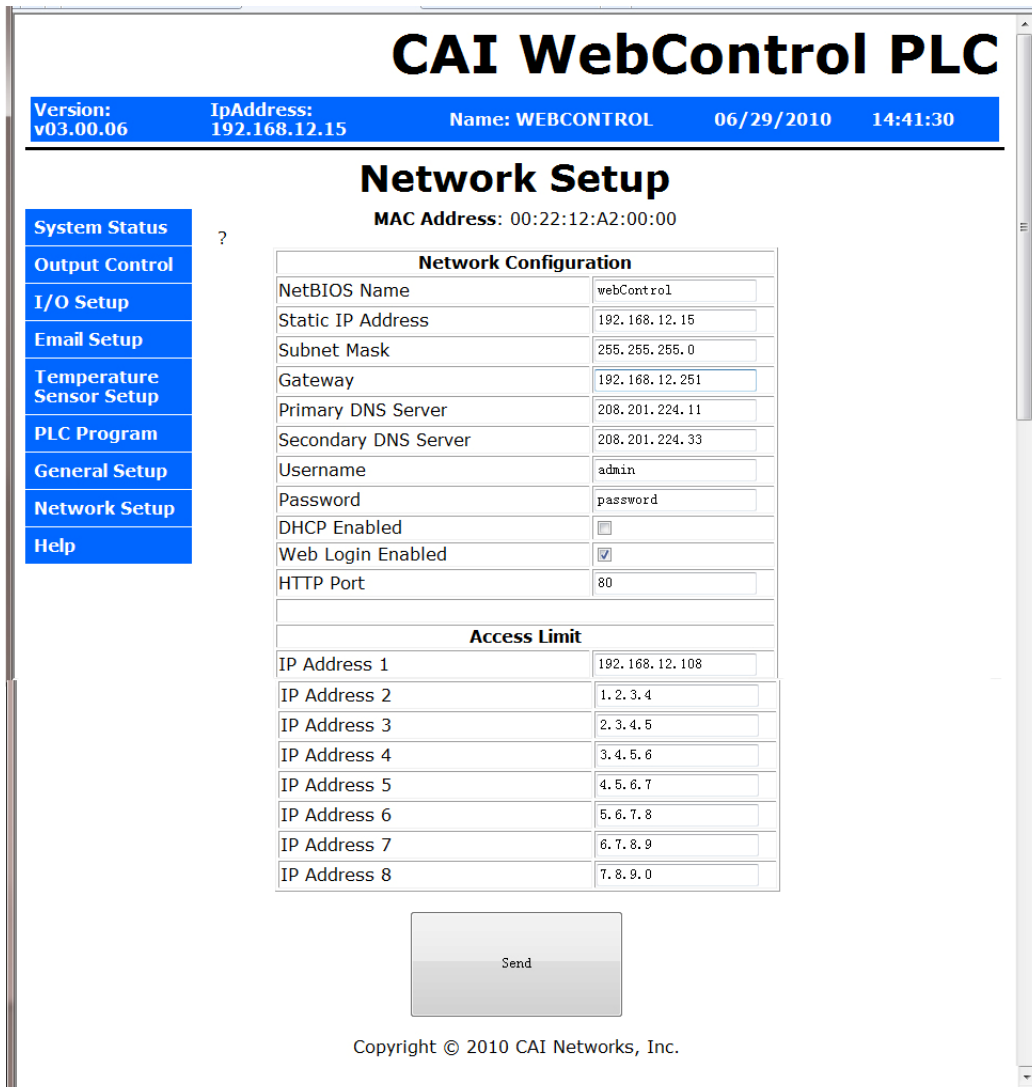
Inputs								
	1	2	3	4	5	6	7	8
TTL Input Bits	0	0	0	0	0	0	0	0
Temperature Sensors	29.5 C	85.1 F	25.2 C	77.3 F	unbound	unbound	unbound	unbound
Temperature Sensor Status	ok	ok	ok	ok	unbound	unbound	unbound	unbound
Analog Inputs	480	239	1					
Humidity Sensor	47 %							

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Figure 3.0 WebControl™ PLC system status

3.1 Network Settings

These are the basic settings that need to be configured in order for WebControl™ to work successfully on a network. It may be necessary to connect the board directly to a PC and access it using its default IP address before connecting directly to a live network in order to configure it correctly. Figure 2.0 shows the connection settings WebControl™ has.



CAI WebControl PLC

Version: v03.00.06 IpAddress: 192.168.12.15 Name: WEBCONTROL 06/29/2010 14:41:30

Network Setup

MAC Address: 00:22:12:A2:00:00

Network Configuration	
NetBIOS Name	webControl
Static IP Address	192.168.12.15
Subnet Mask	255.255.255.0
Gateway	192.168.12.251
Primary DNS Server	208.201.224.11
Secondary DNS Server	208.201.224.33
Username	admin
Password	password
DHCP Enabled	<input type="checkbox"/>
Web Login Enabled	<input checked="" type="checkbox"/>
HTTP Port	80

Access Limit	
IP Address 1	192.168.12.108
IP Address 2	1. 2. 3. 4
IP Address 3	2. 3. 4. 5
IP Address 4	3. 4. 5. 6
IP Address 5	4. 5. 6. 7
IP Address 6	5. 6. 7. 8
IP Address 7	6. 7. 8. 9
IP Address 8	7. 8. 9. 0

Send

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Figure 4.0 WebControl™ PLC Network configurable

3.2 Access Settings

For security purpose, you can decide your own user name and password. For being used over Internet, you may also set the access list, so that only host in the list can access the WebControl board over the network.

3.3 I/O Setup

WebControl™ PLC allows users to directly from browser control each output, or through the PLC logic to control the TTL output. For flexibility, user can decide if the TTL input or out to be inverted between logic 0 and logic 1. To use PLC logic, first user must check the “Global PLC enable” to start the PLC engine. Then for each TTL output, user can decide if the PLC control will be applicable.

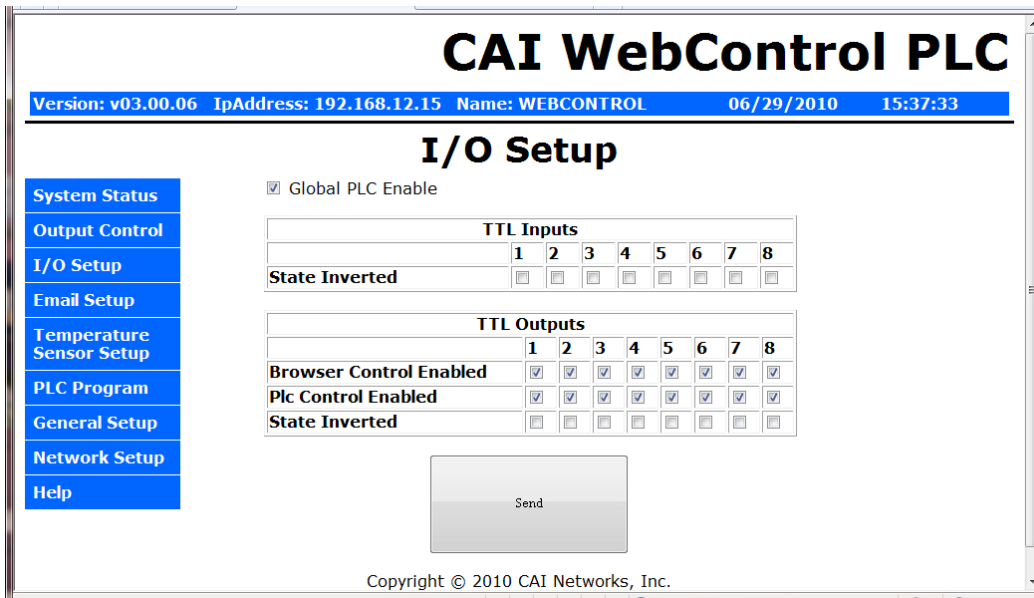


Figure 5.0 I/O setup

WebControl™ PLC allows user using browser to directly control the output state. If a command line utility or third party control software used, you will need to enable the Browser Control for that TTL output, also may need to go to network configuration to disable the Web login (see figure 4.0).

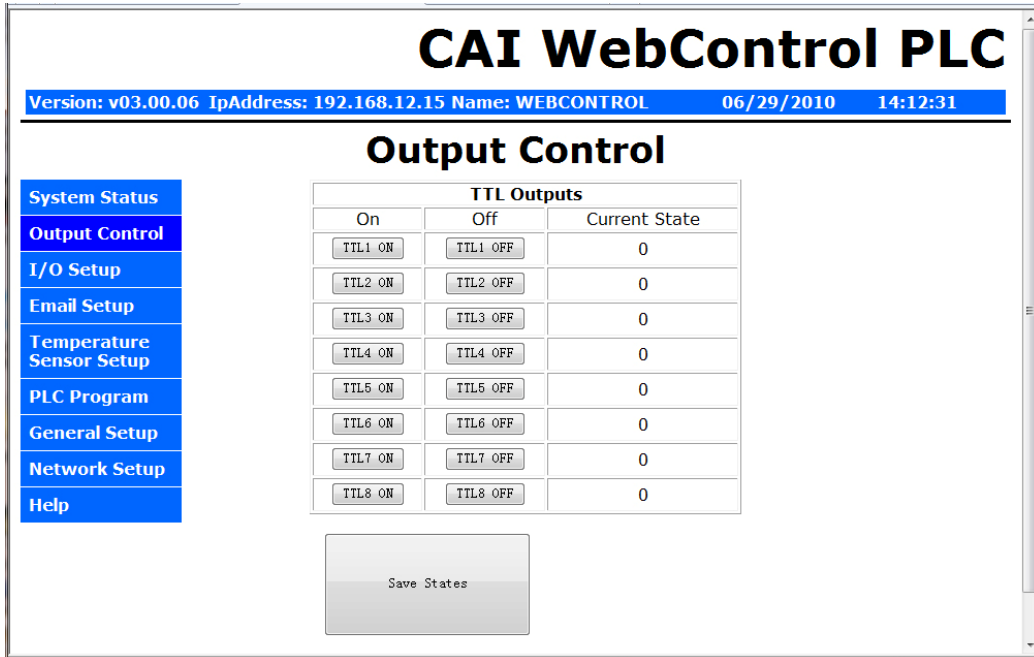


Figure 6.0 WebControl™ Output Control

When click on each TTL output On or Off, the current state of the TTL output will change. However, the display may or may not update depending on the “Web pulling” enabled in the General Setup screen. If you did not enable the “Web Pulling” to save the bandwidth, you will need to use browser refresh to see the output state change. Please note “Save States” button will make WebControl store the state in the EEPROM. When power lost and reapplied, the output will remember the states being saved.

3.4 Email Notification Setup

WebControl™ allows up to 8 different email notification to be send from the PLC program. Please note the port can be any number, but WebControl current hardware can not support SSL enabled email. Certain email servers like Gmail requires use SSL enabled email client. WebControl does not support that.

To many people the email notification problems are either the configuration problem or the SMTP host rejected email. In this version™ PLC firmware, user can send a test email to see if the email notification working or not.

To obtain support for email feature, full TCP capture data is required. The captured data must be able to fully display in WireShark software.

SMTP Email Setup

SMTP Host	192.168.12.113	Port 25
Username (leave blank if none)	my@my-isp.com	
Password (leave blank if none)	mypassword	
To Address	my@myemail.com	
From Address	my@my-isp.com	

Message ID	Message Subject	Message Body	
E1	test email for TTL1	This indicate the TTL 1 has been triggered.	Test
E2			Test
⋮			
E8			Test

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Figure 7.0 WebControl™ email setup

3.5 General Setup

When WebControl™ is connected to the network it will obtain NTP time from Internet. User need to set correct time zone on WebControl™ PLC.

CAI WebControl PLC

Version: v03.00.06	IpAddress: 192.168.12.15	Name: WEBCONTROL	06/29/2010 14:40:16
-----------------------	-----------------------------	------------------	---------------------

General Setup

System Status

Output Control

I/O Setup

Email Setup

Temperature Sensor Setup

PLC Program

General Setup

Network Setup

Help

Clock Setup

Time Zone

Set Date Time

Note: time format MM/DD/YYYY HH:MM:SS

Options

Web Polling Enabled

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Figure 8.0 Network defaults

If the WebControl cannot reach to pool.ntp.org over Internet, it will use its own building clock with less accuracy. User may change and update the clock from this screen.

When Web polling enabled, WebControl™ PLC building active Java code will constantly update the browser display for temperature, humidity, and I/O status. Please note with such a update, it may take significant amount bandwidth from your network, as well as WebControl's processor power.

3.6 Reset Setup

If the configuration was totally mess up, user can reset the board to factory default configuration by shorting the RESET holes while powering up the WebControl™. Reset holes on located between Ethernet port and RS-232 connector. Please note reset will wipe out all the configuration, including the PLC program. Please make sure backup your PLC program before reset. After reset, the login ID and password will be restored to “**admin/password**”. Default IP address 192.168.1.15 with DHCP enabled.

4 AUX System Inputs

The system AUX inputs of WebControl™ are used as inputs to the PLC engine (see section 5.1). This section describes the connector laded as J12. Digital and analog inputs come through J12 connector.

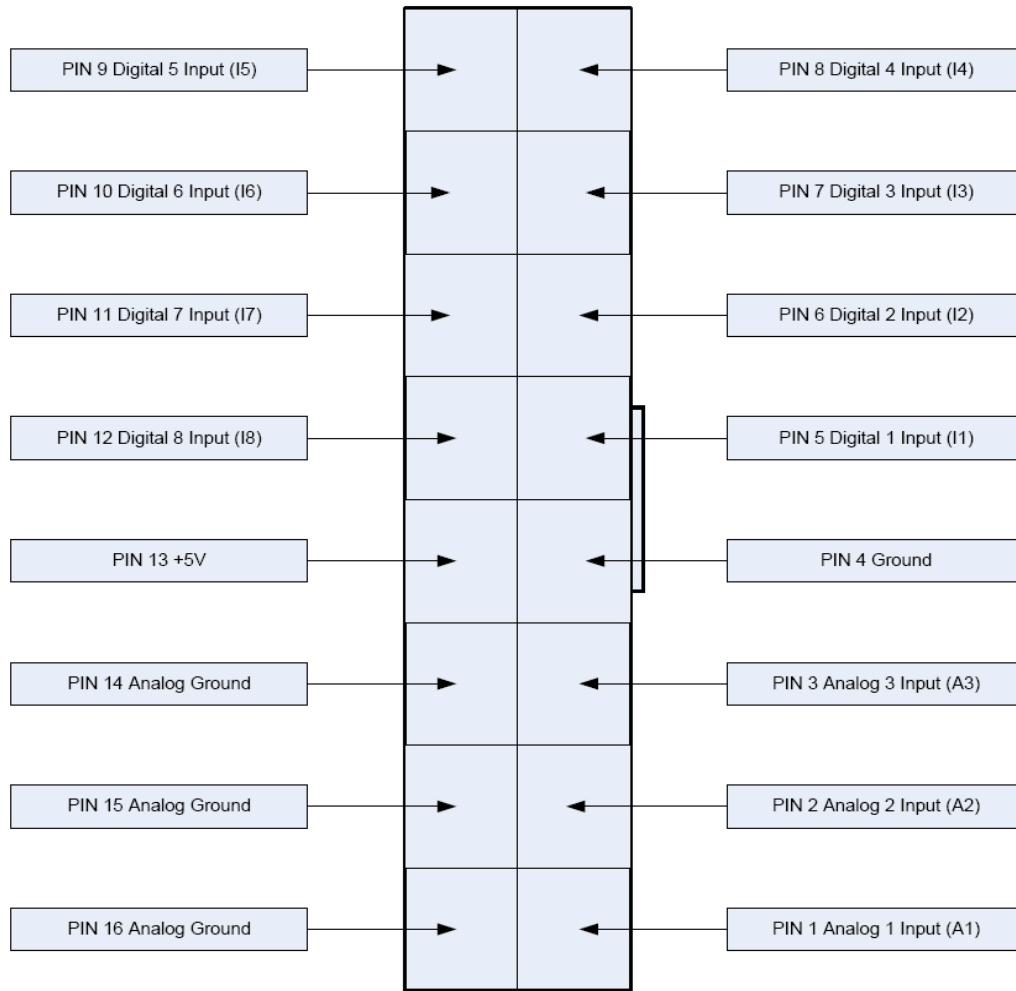


Figure 9.0 WebControl™ J12 Input pins

4.1 Digital Inputs

WebControl™ has eight digital TTL inputs, each of which can be configured to be inverted upon input to the system. The PLC engine will then look for a true or false case of the input. TTL level 0 is defined 0-1.75V; TTL level 1 is defined as 3-5V.

4.2 Analog Inputs

WebControl™ has three analog inputs each having an input voltage range of 0 to +10V. Each analog input can be configured to have an upper and lower threshold which can then be used in the PLC logic. These upper and lower thresholds use the full scale range of 0 – 1023.

4.3 DS1822/DS18B20 1 Wire Temperature Sensors

WebControl™ supports up to eight Maxim DS1822 /DS18B20 12bit 1 wire temperature sensors. Each temperature sensor must be first assigned a temp sensor number T1-T8.

CAI WebControl PLC

Version: v03.00.06 IpAddress: 192.168.12.15 Name: WEBCONTROL 06/29/2010 14:31:15

Temperature Sensor Setup

Configured Sensors		
Sensor	ROM Code	Units
T1	28BFD5B70100	<input checked="" type="radio"/> °C <input type="radio"/> °F
T2	000000000000	<input type="radio"/> °C <input checked="" type="radio"/> °F
T3	28BFD5B70100	<input checked="" type="radio"/> °C <input type="radio"/> °F
T4	28AB0DF60100	<input type="radio"/> °C <input checked="" type="radio"/> °F
T5	000000000000	<input checked="" type="radio"/> °C <input type="radio"/> °F
T6	000000000000	<input checked="" type="radio"/> °C <input type="radio"/> °F
T7	000000000000	<input checked="" type="radio"/> °C <input type="radio"/> °F
T8	000000000000	<input checked="" type="radio"/> °C <input type="radio"/> °F

Send

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Figure 10.0 WebControl™ Temperature sensor assignment

Each temp sensor has unique ROM code. One temp sensor can be assigned for different sensor number. User can also select the unit as centigrade or ferinheight. If sensor failed later due to sensor failure or wire problem, WebControl™ will display the state as failed, but keep the last valid sensor value. This is to prevent the PLC logic turn on heater/cooler or motor undesirably.

4.4 Honeywell 4000 Series Relative Humidity Sensor

The WebControl™ hardware is designed to support one Honeywell 4000 series relative humidity sensor. The Honeywell sensor output is 'almost' linear voltage between 0 - +5V dc proportional to the relative humidity. This output is fed into one of the A/D converter channels on the microcontroller. CGI command codes are available to setup an upper and lower threshold for the humidity sensor that can then be used in the Boolean expressions.

WebControl PLC has calibrated the humidity curve at 11%, 25%, 45%, and 78%. However, due to sensor differences, some sensors may read the humidity value

different from actual value. Adding a 5K linear potentiometer (pot) in series with pin 3 (5V supply line) can help user to adjust your sensor match the accurate humidity reading. If the humidity reading varies a lot, that is an indication your power supply is not providing enough voltage to the board.

4.5 Timers

WebControl™ PLC different from BRE engine, user must write PLC code to implement timers and delay functions. There is no hard limit of number of timers and delays, but the PLC code space of total 4000 line of code and variables can be used at the same time are limited.. WebControl PLC has build-in timer value for comparison:

- ❑ CD Current date mm/dd/yyyy format
- ❑ CT Current time hh:mm:ss format
- ❑ CDW Current day of week
- ❑ CH Current hour of day
- ❑ CM Current minute of hour
- ❑ CS Current second of minute
- ❑ CDAY Current day of month
- ❑ CMONTH Current month of year
- ❑ CYEAR Current year

WebControl timer variables are in one milli-second minimum resolution. However, due to high priority I/O like handling, like 1-wire interrupt, the accuracy of the timer may in the range greater than 10mS. For how to program the timer functions, please read Chapter 6 completely. There are a few examples described how to program the WebControl PLC to act based on the input conditions and timer conditions.

4.6 Direct Query System Inputs and Outputs

To integrate with other servers, directly query I/O status maybe desirable. Using wget command from other servers or computers, user can directly query each input and output status. The following HTTP commands are directly return the I/O values:

“geta1.cgi, geta2.cgi, geta3.cgi” – to query analog input values

“geth1.cgi” – to query the humidity sensor readings

“geti1.cgi, geti2.cgi,..geti8.cgi” – to query each digital input values

“geto1.cgi, geto2.cgi,..geto8.cgi” – to query each TTL output status

“gett1.cgi, gett2.cgi,...gett8.cgi” – to query each temperature sensor value

“getts1.cgi, getts2.cgi,...getts8.cgi” – to query each temperature sensor status

5 Real Time Clock

WebControl™ has a build-in clock functions that is kept accurate by using an atomic clock via the simple network timer protocol (SNTP). Configuration is required to set the correct time zone of the clock. CGI commands are provided to do this. When NTP is not available, WebControl™ will use its own crystal to maintain the clock accuracy. If NTP is available, only need to set the time zone in the clock page. If NTP is not available, please set your local clock in the clock page also. Without NTP, its internal clock may not as accurate.

5.1 Network Requirements to Use the NTP

WebControl™ must be connected to a network that has access to a DNS server. The primary and secondary DNS server addresses of WebControl™ are required to be configured correctly. WebControl™ will use DNS to resolve the name of the timeserver. The NTP server WebControl accessing is pool.ntp.org. If internal NTP server must be used, DNS server must resolve the name record for pool.ntp.org to your local NTP server's IP address.

6 WebControl™ PLC Programming

The WebControl™ PLC firmware can be programmed to execute programmable logic sequences, including comparison and sub routines. This is the major change from the BRE(Booleam Run Engine) version firmware. WebControl™ PLC uses assembly like PLC language. It starts with “START” and finishes with “END”. The PLC program is pasted into the web GUI. WebControl will automatically store it into its EEPROM so that if recycle power will not lose the program. The limitation of the PLC is 4000 line of code. The support for PLC programming is not included in the free support for configuration of WebControl™ PLC.

6.1 The Basics of PLC Programming

A PLC program is made up of main routine and optional subroutines.

The main routine is enclosed between mandatory START and END instructions e.g.

```
START
#main instructions go here
END
```

If sub routines are used then they are listed after the main routine body. Sub routines start at their label and must end with the instruction RET e.g.

```
TEST_IO_SUB:
#instructions here
RET
```

Subroutines can be called from the main program and from within other subroutines.

Note that WebControl PLC has a program return address stack depth of 8.

The program control block has a zero bit that is updated implicitly on most instructions. This zero bit can also be used implicitly when using branch and call instructions. E.g. the following test instruction yields a Boolean result which will implicitly set the state of the zero bit. Next a branch instruction is used which branches on the state of the zero bit.

```
TSTEQ IP1 1 # sets zero bit based on the result of the test instruction
BNZ label # branches to label if zero bit is non-zero
```

Format of instructions:

label: (optional)

opcode operands

Labels must be terminated with a colon ':' and can be a maximum of 10 characters.

6.2 WebControl™ PLC Instructions

The following symbols are used in the table below:

d = destination

a,b..c = operands

() = optional, any operand enclosed in parenthesis mean it is an optional operand.

[] = delay operator always optional. When the delay operator is used on input operands the current value of that input is only used if it has had that value for greater than the delay period specified between the brackets. When this operator is used on an output operand the output value is only set for the period specified in the brackets. All delay periods are specified in milliseconds. Note that accuracy and timer resolution is approximately 100ms, even the delay operator value is in unit of 1mS..

Opcode	Operands	Description
START		Start of main program
TSTEQ	a[] b[] (d[])	Tests if a is equal to b. Boolean result loaded into optional destination (d). Zero bit updated with result. If test evaluates to false then the next instruction is skipped.
TSTNE	a[] b[] (d[])	Tests if a is NOT equal to b. Boolean result loaded into optional destination (d). Zero bit updated with result. If test evaluates to false then the next instruction is skipped.
TSTGT	a[] b[] (d[])	Test if a is greater than b. Boolean result loaded into optional destination (d). Zero bit updated with result. If test evaluates to false then the next instruction is skipped.
TSTLT	a[] b[] (d[])	Tests if a is less than b. Boolean result loaded into optional destination (d). Zero bit updated with result. If test evaluates to false then the next instruction is skipped.
TSTGE	a[] b[] (d[])	Tests if a is greater than OR equal to b. Boolean result loaded into optional destination (d). Zero bit updated with result. If test evaluates to false then the next instruction is skipped.
TSTLE	a[] b[] (d[])	Tests if a is less than OR equal to b. Boolean result loaded into optional destination (d). Zero bit updated with result. If test evaluates to false then the next instruction is skipped.
SET	a[] b[]	Sets I/O id a to the value of b.
ADD	a[] b[] d[]	Adds a and b and puts the result into d. Zero bit updated with result.
SUB	a[] b[] d[]	Subtracts b from a and puts the result into d. Zero bit updated with result.
DIV	a[] b[] d[]	Divides a by b and puts the result into d. Zero bit updated

		with result.
MUL	a[] b[] d[]	Multiplies a by b and puts the result into d. Zero bit updated with result.
DEC	a	Decrements a by 1. Zero bit updated.
INC	a	Increments a by 1. Zero bit updated.
AND	a[] b[] (d[])	Logical AND's a with b and optionally puts boolean result into d. Zero bit updated.
OR	a[] b[] (d[])	Logical OR's a with b and optionally puts boolean result into d. Zero bit updated.
XOR	a[] b[] (d[])	Logical XOR's a with b and optionally puts boolean result into d. Zero bit updated.
BNZ	(a) b	If the optional a operand is specified it is tested for a non zero value. If a is not specified then the zero bit is tested for non zero. If true then program jumps to label specified in operand b.
BZ	(a) b	Same as BNZ but tests for zero value.
CNZ	(a) b	Same as the branch instruction but calls a subroutine instead of branching. See section on program address stack.
CZ	(a) b	Same as above but tests for zero result.
CALLSUB	a	Calls subroutine with label a. See section on program address stack.
GOTO	a	Branches to program address specified by label a.
DELAY	a	Delay instruction, delay specified in 1/1000 seconds.
NOP		A no operation instruction.
RET		A return from subroutine instruction.
EMAIL	a	Sends email, a = index of message to send.
END		End of main program. This instructions will set the program counter back to zero and the program will start executing from the beginning.

Operands

An operand can be any of the following:

- a signed 32 bit decimal number. e.g. 100 or 1 or 0 etc.
- a hexadecimal number. e.g. 0xABF.
- a date stamp in the format MM/DD/YYYY e.g 02/10/2010
- a time stamp in the format HH:MM:SS e.g. 20:25:00
- a day of week identifier enclosed in single quotes e.g. 'sun'. Day of week identifiers are 'sun' 'mon' 'tue' 'wed' 'thu' 'fri' 'sat'
- an I/O identifier that is a place holder for the real I/O value that the PLC engine will get at runtime. Valid I/O identifiers are explained next below.

6.3 WebControl™ PLC I/O Identifiers

The following are the valid I/O identifiers

OP1	TTL Outputs 1...8	Valid range 0 - 1
OP2		
OP3		
OP4		
OP5		
OP6		
OP7		
OP8		
IP1	TTL Inputs 1...8	Valid range 0 - 1
IP2		
IP3		
IP4		
IP5		
IP6		
IP7		
IP8		
AIP1	Analog Inputs 1...3	Valid range 0 - 1024
AIP2		
AIP3		
T1	Temperature sensor inputs 1...8	Valid range -550 - +1250.
T2	Note that temperature values are specifies in 10's of degrees. So to test	
	for 21.6 degrees C you would use the value 216.	
T3		
T4		
T5		
T6		
T7		
T8		
H1	Humidity sensor	valid range 0 - 100
EM1	Email identifiers 1...8	
EM2		
EM3		
EM4		
EM5		
EM6		
EM7		
EM8		
CD	Current date	mm/dd/yyyy format
CT	Current time	hh:mm:ss format
CDW	Current day of week	
CH	Current hour of day	

CM	Current minute of hour
CS	Current second of minute
CDAY	Current day of month
CMONTH	Current month of year
CYEAR	Current year
VAR1	32 bit signed integer variables 1...8
VAR2	
VAR3	
VAR4	
VAR5	
VAR6	
VAR7	
VAR8	
RAM1	32 bit signed integer general purpose RAM 1...8. Delay operator not valid on these.
RAM2	
RAM3	
RAM4	
RAM5	
RAM6	
RAM7	
RAM8	

6.4 WebControl PLC Examples

Sets output 1 if temperature T3 is greater than 20.6 degrees and clears OP1 if T3 is less than 20.6 degrees.

```
START
TSTGT T3 206 OP1
END
```

Flashes output 2 at a rate of 1Hz. (Please note OP2[500] has no space in between).

```
START
TSTEQ OP2 0 OP2[500]
END
```

To setup a momentary output on OP3 of 1 second the following rule should be used: Note you may change the momentary length to 0.5s by change the value from [1000] to [500]. OP3[1000] has no space in between.

```
START
TSTEQ OP3[1000] 1
SET OP3 0
END
```

To send email 1 when $T3 - T2 \geq 20$ degrees you would use:

```
START
SUB T3 T2 RAM1
TSTGE RAM1 200 EM1
END
```

The above rule is a bit too simple because an email will constantly be generated while RAM1 is greater than or equal to 200. (20 degrees in this case) So to guard against that the following logic should be implemented:

```
START
    SET RAM2 0
LOOP:
    SUB T3 T2 RAM1
    TSTGE RAM1 200 RAM1
    GOTO SEND
    SET RAM2 0
    GOTO LOOP
END

SEND:
    TSTEQ RAM2 0 RAM2
    EMAIL 1
    GOTO LOOP
```

6.4.1 WebControl PLC Example 1, Parallel I/O

This simple program performs 4 separate I/O checks and sets O1 to O4 states depending on the state of some inputs.

- OP1 is set if $T3 > 50$
- OP1 is cleared if $T3 < 50$
- OP2 is set if $IP1 == 1$ for more than 300ms
- OP2 is cleared if $IP1 == 0$
- OP3 is set if $AIP1 + AIP2 > 1024$
- OP3 is cleared if $IP4 == 1$
- OP4 is set if $OP1 == 1$
- OP4 is cleared if $OP1 == 0$

The assembly language written for the above scenarios would be as follows:

```
START:
```



```

CALLSUB checkOP1
CALLSUB checkOP2
CALLSUB checkOP3
CALLSUB checkOP4
GOTO start
END

checkOP1:
  TSTGT T3 500 O1
  RET

checkOP2:
  TESTEQ IP1[300] 1 OP2
  RET

checkOP3:
  AND AIP1 AIP3 RAM1
  TSTGT RAM 1024
  BNZ I1
  TSTEQ IP4 1
  BNZ I2
  RET

I1:
  SET O3 1
  RET

I2:
  SET O3 0
  RET

checkOP4:
  TSTEQ OP1 1 OP4
  RET

```

6.4.2 WebControl PLC Example 2, Sequential I/O

The following simple program shows how to set-up sequential I/O.

```

OP1 is set when IP1 rises from 0 to 1
OP4 is cleared when IP1 rises from 0 to 1
OP1 is cleared when O4 == 1
OP2 is set when T3 > 25 AND OP1 == 1
OP2 is cleared when OP1 == 0
EMAIL1 is sent when OP2 is set
O4 is set when OP2 == 1 for more than 1 second

```

The assembly language written for the above scenario would be as follows:

```
START
```

```

      BNZ IP1 start
11:   TST IP1 1
      BZ 11
      SET OP1 1
      SET OP4 0

12:   TSTGT T3 250 RAM1
      AND OP1 RAM1
      BZ 12
      SET OP2 1
      EMAIL 1

13:   TSTEQ OP2[1000] 1
      BZ 13
      SET OP4 1
      SET OP1 0
      END

```

6.4.3 WebControl PLC Example 3, Traffic Lights

This example will let pedestrian to push a button to change the light on a busy street, so that he can cross the street safely. IP1 hooks up to the pedestrian crossing button. If someone pushed cross button, the street will have amber light on for 10 seconds, then red light to stop all the cars, allowing pedestrian to cross street in next 30 seconds. At the end of 30 seconds, it will flash the amber and red light for 5 seconds. VAR1 in the main program will let the crossing light turn on every 100 seconds, does not matter anybody push the crossing button or not.

OP1 Red + Pedestrian crossing light

OP2 Amber

OP3 Green

IP1 Pedestrian Push Button

```

      START
      CALLSUB LIGHTS_GO

loop: SET VAR1[10000] 1

loop1: TSTEQ IP1 1
      BNZ sr

```

```
BZ VAR1 sr  
GOTO loop1
```

sr:

```
CALLSUB STOP  
GOTO loop  
END
```

LIGHTS_ST:

```
SET OP1 1  
SET OP2 0  
SET OP3 0  
RET
```

LIGHTS_GO:

```
SET OP1 0  
SET OP2 0  
SET OP3 1  
RET
```

LIGHTS_AM:

```
SET OP1 0  
SET OP2 1  
SET OP3 0  
RET
```

STOP:

```
CALLSUB LIGHTS_AM  
DELAY 5000  
CALLSUB LIGHTS_ST  
DELAY 60000  
CALLSUB LIGHTS_AM  
SET RAM2 5
```

flash:

```
XOR OP2 1 OP2  
DELAY 500  
DEC RAM2  
BNZ flash  
CALLSUB LIGHTS_GO
```

RET

6.4.4 WebControl PLC Example 4, Time based Control

This example will have four subroutines. WebControl PLC will continuously loop through them. The “hourly” routing will compare analog input 1 and analog input 2, if $A1 > A2$, send an email notice 1. You can use similar logic to adjust your solar panel orientation each hour, etc. The “period” subroutine will turn on night light after 18 hours and turn it off at 5AM. The “monthly” routing will check the “salt low” sensor AIP3 on the water softener and send email notice 2. The “yearly” routing will ring the New Year’s bell connected to OP8 on each and every New Year’s Day for the whole day!

```

start
    callsub hourly
    callsub period
    callsub monthly
    callsub yearly
end
hourly:
    tstne RAM1 CH
    goto t1
ret
t1:
    set RAM1 CH
    TSTGT AIP1 AIP2
    EMAIL 1
ret
period:
    tstge ch 18 RAM2
    nop
    tstle ch 5 RAM3
    nop
    OR RAM2 RAM3 OP3
ret
monthly:
    tstne RAM4 CMONTH
    goto t2
ret
t2:
    set RAM4 CMONTH
    TSTLT AIP3 20
    EMAIL 2
ret
yearly:
    tsteq CMONTH 1 RAM2
    nop
    tsteq CDAY 1 RAM3
    nop

```

```

AND RAM2 RAM3 OP8
ret

```

6.4.5 WebControl PLC Example 5, Battery Charger

This is a PLC program to charge 3 serially connected NiMH batteries. First, it tries to discharge the batteries individually. If any battery discharged to 1V, it will stop the discharge and start charging. When each cell being charged to 1.25V, it will stop charging. We assume the A1, A2, and A3 being calibrated to 1V=100. The measurement on the battery 2 is the total voltage of battery 1 and battery 2. And the measurement on battery 3 is the total voltage of all three batteries. This example will individually discharge and charge each battery.

```

start
    set op1 1
    set op2 1
    set op3 1
    set RAM1 0
    set RAM2 0
    set RAM3 0
loop:
    cnz o1 check_b1
    cnz o2 check_b2
    cnz o3 check_b3
goto loop
end
check_b1:
    BNZ RAM1 c1
    tstle A1 100 RAM1
    bz e1
c1:
    tstgt A1 125
    bnz e1
    set o1 0
    set o4 1
e1:
ret
check_b2:
    BNZ RAM2 c2
    sub A2 A1 RAM4
    tstle RAM4 100 RAM2
    bz e2
c2:
    sub A2 A1 RAM4
    tstgt RAM4 125
    bnz e2
    set o2 0
    set o5 1
e2:

```

```

ret
check_b3:
    BNZ RAM3 c3
    sub A3 A2 RAM4
    sub RAM4 A1 RAM4
    tstle RAM4 100 RAM3
    bz e3
c3:
    sub A3 A2 RAM4
    sub RAM4 A1 RAM4
    tstgt RAM4 125
    bnz e3
    set o3 0
    set o6 1
e3:
ret

```

6.4.6 WebControl PLC Example 6, RFID reader and browser Control

For office door using RFID reader, as well as allowing operator remote browser control, the following program provided the example. RFID reader's NC (normally connect) output connects to IP1 on WebControl digital input. A 2.2K pull-up resistor also connected between IP1 and 5V. In this way, each time a valid RFID tag sensed, a TTL "1" feeds to WebControl IP1. Remote operator can also open the door by using browser set OUTPUT TTL1 to on. OP1 connects to the door open switch. TESTEQ logic will make sure the OP1 is an 1 second momentary output.

"LIGHTS" subroutine is for light control outside the office door; the light is on at 7PM and off at 5AM.

```

START
    CALLSUB LIGHTS
    TSTEQ RAM1 0
    CALLSUB SET_OP1
    CALLSUB CHK4LOW
    TSTEQ OP1[1000] 1
    SET OP1 0
END

```

```

CHK4LOW:
    TSTEQ IP1 0

```

```
SET RAM1 0  
RET
```

SET_OP1:

```
TSTEQ IP1 1 RAM1  
SET OP1 1  
RET
```

LIGHTS:

```
TSTGE CH 19 RAM2  
NOP  
TSTLE CH 5 RAM3  
NOP  
OR RAM2 RAM3 OP3  
RET
```